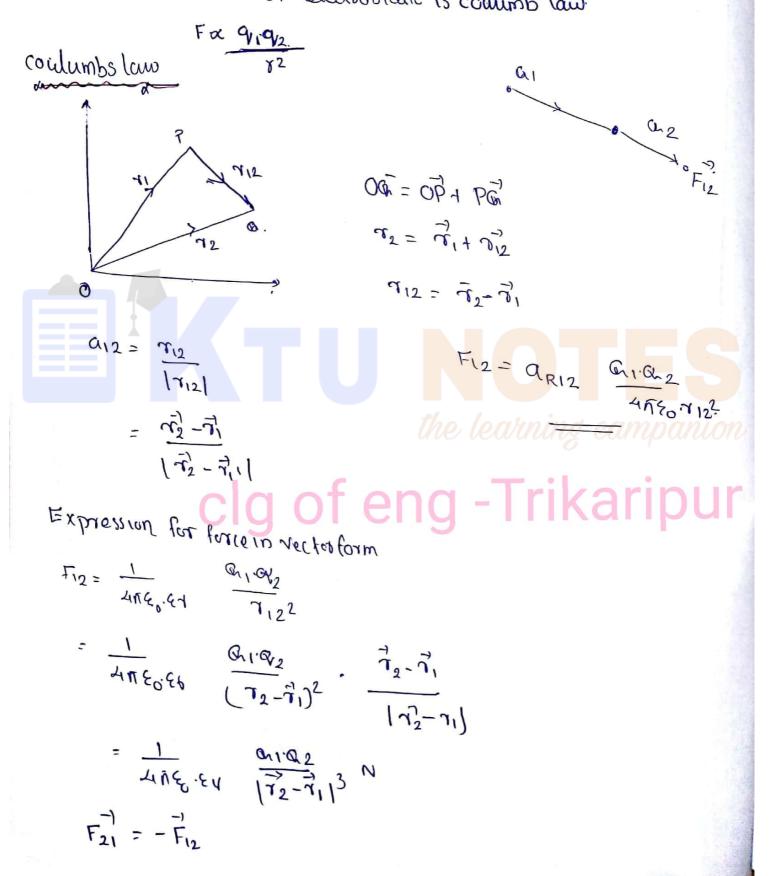
MODULE -

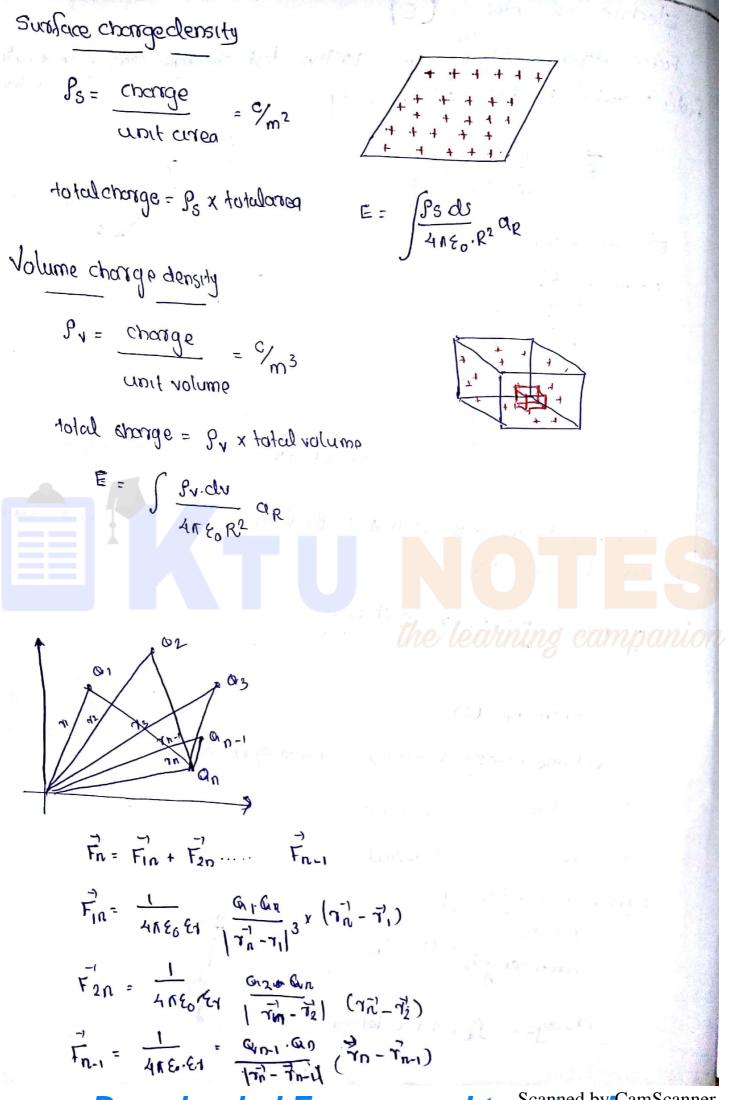
Electrostatic is the branch of electromagnetics dealing with the effects of electric charges at rest The fundamental law of electrostatic is coulimb law

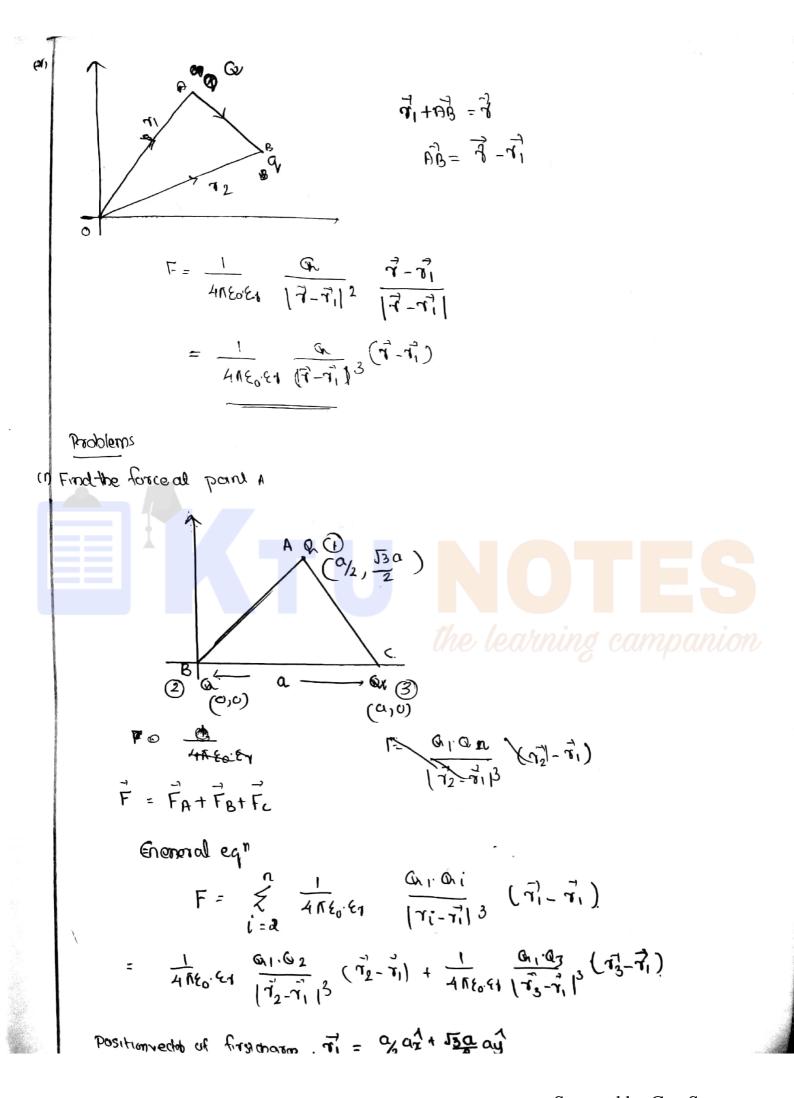


Electric field indensity (E)
Force expressioned by unit positive test change ploted in a electric
field is called clearly field intensity

$$\vec{E} = \frac{1}{4\pi\epsilon_0\epsilon_1} \cdot \frac{\kappa}{\pi^2}$$

Electric field:
 $\vec{E} = \frac{1}{4\pi\epsilon_0\epsilon_1} \cdot \frac{\kappa}{\pi^2}$
 $\vec{E} = \frac{1}{4\pi\epsilon_0\epsilon_1} \cdot \frac{\kappa}{\pi^2}$
 $\vec{E} = \frac{1}{4\pi\epsilon_0\epsilon_1} \cdot \frac{\kappa}{\pi^2}$
conterpt of hest incruge :+ Small and positive
Does not affect change distribution
(a) Direction of electricities is these of the force that caching on a unit
positive test change
(a) point changes (c)
(c) point changes (c)
(c) point changes (c)
(c) point changes (c)
(c) a surface changes (c/m³) \leq most general
(c) surface changes (c/m³)
(d) the changes (c/m³)
 ϵ most general
(e) change density
 $\frac{1}{1+\epsilon_0}\epsilon_1 = f_1 = f_1$
 $\frac{1}{1+\epsilon_0}\epsilon_1 = f_1 = f_1$





$$\begin{aligned} \mathbf{r}_{\mathbf{J}}^{\mathbf{z}} &= \mathbf{0} \\ \mathbf{r}_{\mathbf{J}}^{\mathbf{z}} &= \mathbf{a} \cdot \mathbf{a}_{\mathbf{J}}^{\mathbf{z}} \\ &= \frac{1}{4\pi\epsilon_{\mathbf{b}}\epsilon_{\mathbf{t}}} \cdot \frac{\mathbf{a}_{\mathbf{t}} \cdot \mathbf{a}_{\mathbf{z}}}{\left[\mathbf{a}_{\mathbf{z}}^{\mathbf{z}} + \frac{\mathbf{b}_{\mathbf{a}}}{\mathbf{a}}\right]} \begin{pmatrix} (\mathbf{a}_{\mathbf{b}})^{\mathbf{z}} + \frac{1}{3}\mathbf{a}_{\mathbf{a}} + \frac{1}{4\pi\epsilon_{\mathbf{b}}\epsilon_{\mathbf{t}}} \cdot \frac{\mathbf{a}_{\mathbf{t}} \cdot \mathbf{a}_{\mathbf{s}}}{\left[\mathbf{a} \cdot \mathbf{a}_{\mathbf{z}}^{\mathbf{z}} + \frac{\mathbf{b}_{\mathbf{s}}}{\mathbf{a}}\right]} \\ &= \frac{1}{4\pi\epsilon_{\mathbf{b}}\epsilon_{\mathbf{t}}\epsilon_{\mathbf{t}}} \frac{\mathbf{a}_{\mathbf{b}}^{\mathbf{z}}}{\left[\mathbf{a}_{\mathbf{z}}^{\mathbf{z}} + \frac{\mathbf{b}_{\mathbf{a}}}{\mathbf{a}}\right]} = \frac{1}{4\pi\epsilon_{\mathbf{b}}\epsilon_{\mathbf{t}}\epsilon_{\mathbf{t}}} \left[\frac{\mathbf{a}_{\mathbf{z}}^{\mathbf{z}}}{\left(\mathbf{a}_{\mathbf{a}}\right)^{\mathbf{z}}} - \frac{\mathbf{a}_{\mathbf{z}}^{\mathbf{z}}}{\left(\mathbf{a}_{\mathbf{z}}^{\mathbf{z}} + \frac{\mathbf{b}_{\mathbf{a}}}{\mathbf{a}}\right]} \right] \\ &= \frac{1}{4\pi\epsilon_{\mathbf{b}}\epsilon_{\mathbf{b}}\epsilon_{\mathbf{t}}} \left[\frac{\mathbf{a}_{\mathbf{z}}^{\mathbf{z}}}{\left(\mathbf{a}_{\mathbf{a}}\right)^{\mathbf{z}}} - \frac{\mathbf{a}_{\mathbf{z}}^{\mathbf{z}}}{\left(\mathbf{a}_{\mathbf{z}}^{\mathbf{z}} - \frac{\mathbf{b}_{\mathbf{z}}}{\mathbf{a}}\right]} \right] \\ &= \frac{1}{4\pi\epsilon_{\mathbf{b}}\epsilon_{\mathbf{b}}\epsilon_{\mathbf{t}}} \left[\frac{\mathbf{a}_{\mathbf{a}}}{\mathbf{a}}\right] - \frac{\mathbf{a}_{\mathbf{z}}^{\mathbf{z}}}{\left(\mathbf{a}_{\mathbf{a}}^{\mathbf{z}} - \frac{\mathbf{b}_{\mathbf{z}}}{\mathbf{a}}\right]} \\ &= \frac{1}{4\pi\epsilon_{\mathbf{b}}\epsilon_{\mathbf{b}}\epsilon_{\mathbf{t}}} \left[\frac{\mathbf{a}_{\mathbf{a}}}{\mathbf{a}^{\mathbf{z}}} - \frac{\mathbf{b}_{\mathbf{a}}^{\mathbf{z}}}{\left(\mathbf{a}_{\mathbf{a}}^{\mathbf{a}}\right)^{\mathbf{z}}} - \frac{\mathbf{b}_{\mathbf{a}}^{\mathbf{z}}}{\mathbf{a}}\right] \\ &= \frac{1}{4\pi\epsilon_{\mathbf{b}}\epsilon_{\mathbf{b}}\epsilon_{\mathbf{t}}} \left[\frac{\mathbf{a}_{\mathbf{a}}}{\mathbf{a}^{\mathbf{a}}} - \frac{\mathbf{b}_{\mathbf{a}}^{\mathbf{a}}}{\left(\mathbf{a}_{\mathbf{a}}^{\mathbf{a}}\right) - \frac{\mathbf{b}_{\mathbf{a}}}{\mathbf{a}}} \right] \\ &= \frac{1}{4\pi\epsilon_{\mathbf{b}}\epsilon_{\mathbf{b}}\epsilon_{\mathbf{t}}} \left[\frac{\mathbf{a}_{\mathbf{a}}}{\mathbf{a}^{\mathbf{a}}} \left(-\frac{\mathbf{b}_{\mathbf{a}}}{\mathbf{a}^{\mathbf{a}}}\right) - \frac{\mathbf{b}_{\mathbf{a}}}{\mathbf{a}}} \left(\frac{\mathbf{a}_{\mathbf{a}}}{\mathbf{a}^{\mathbf{a}}}\right) \right] \\ &= \frac{1}{4\pi\epsilon_{\mathbf{b}}\epsilon_{\mathbf{b}}\epsilon_{\mathbf{t}}} \left[\frac{\mathbf{a}_{\mathbf{a}}}{\mathbf{a}^{\mathbf{a}}} \left(-\frac{\mathbf{b}_{\mathbf{a}}}{\mathbf{a}^{\mathbf{a}}}\right] \\ &= \frac{1}{4\pi\epsilon_{\mathbf{b}}\epsilon_{\mathbf{b}}\epsilon_{\mathbf{t}}} \left[\frac{\mathbf{a}_{\mathbf{a}}}{\mathbf{a}^{\mathbf{a}}} \left(-\frac{\mathbf{b}}{\mathbf{a}^{\mathbf{a}}}\right) - \frac{\mathbf{b}_{\mathbf{a}}}{\mathbf{a}}\right] \\ &= \frac{1}{4\pi\epsilon_{\mathbf{b}}\epsilon_{\mathbf{b}}\epsilon_{\mathbf{t}}} \left[\frac{\mathbf{a}_{\mathbf{a}}}{\mathbf{a}^{\mathbf{a}}} \left(-\frac{\mathbf{b}}{\mathbf{a}^{\mathbf{a}}}\right) - \frac{\mathbf{b}_{\mathbf{a}}}{\mathbf{a}}\right] \\ &= \frac{1}{4\pi\epsilon_{\mathbf{b}}\epsilon_{\mathbf{b}}\epsilon_{\mathbf{t}}} \left[\frac{\mathbf{a}_{\mathbf{b}}}{\mathbf{a}^{\mathbf{b}}} \left(\frac{\mathbf{b}}{\mathbf{a}^{\mathbf{b}}}\right) \\ &= \frac{1}{4\pi\epsilon_{\mathbf{b}}}\frac{\mathbf{a}_{\mathbf{b}}}{\mathbf{a}^{\mathbf{b}}} \left(\frac{\mathbf{b}}{\mathbf{a}^{\mathbf{b}}}\right) \\ &= \frac{1}{4\pi\epsilon_{\mathbf{b}}}\frac{\mathbf{a}_{\mathbf{b}}}{\mathbf{a}^{\mathbf{b}}} \left(\frac{\mathbf{b}}{\mathbf{a}^{\mathbf{b}}}\right) \\ &= \frac{1}{4\pi\epsilon_{\mathbf{b}}}\frac{\mathbf{a}_{\mathbf{b}}}{\mathbf{a}^{\mathbf{b}}} \left(\frac{\mathbf{b}}{\mathbf{a}^{\mathbf{b}}}\right) \\ &= \frac{1}{4\pi\epsilon_{\mathbf{b}}}\frac{\mathbf{a}_{\mathbf{b$$

$$F = \frac{1}{2} \frac{1}{4\pi \xi_0 \xi_1} \frac{\alpha_1 \cdot \omega_1}{|\tau_1 - \tau_1|^3} (\overline{\tau}_1 - \overline{\tau}_1)$$

$$P = \frac{1}{\tau_1} = \alpha \cdot \alpha_1^4 + \alpha_1^2 \alpha_2^2$$

$$P = \frac{1}{\tau_2} = \alpha \cdot \alpha_1^4$$

$$P = \frac{1}{4\pi \xi_0 \cdot \xi_1} \frac{\omega_2^3}{\alpha^2 - \omega_1^2}$$

$$P = \frac{1}{4\pi \xi_0 \cdot \xi_1} \frac{\omega_2^3}{\alpha^2 - \omega_1^2}$$

$$P = \frac{1}{4\pi \xi_0 \cdot \xi_1} - \alpha \cdot \alpha_1^4$$

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$$P = \frac{1}{4\pi \xi_0 \cdot \xi_1} - \frac{\omega_2^2}{\alpha_3} \cdot (-\alpha \cdot \alpha_1^4)$$

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$$= -\frac{1}{4\pi\epsilon_{0}\epsilon_{1}} \frac{G^{2}}{G^{2}} \left(\alpha_{0} \alpha_{1}^{2} + \alpha_{1} \alpha_{2}^{2} \right) \left[1 + \frac{1}{\alpha_{1} f_{2}} \right]$$

$$= \left[\left(\frac{1}{\sqrt{3} f_{2}} \right) \left[\left(\frac{1}{4\pi\epsilon_{0}\epsilon_{1}}, \frac{G^{2}}{\alpha_{2}}, \alpha_{2}^{2} + \frac{1}{\sqrt{4\pi\epsilon_{0}}\cdot\epsilon_{4}}, \frac{G^{2}\Omega_{2}^{2}}{\alpha_{2}}, \alpha_{2}^{2} \right) \right] + \frac{1}{\sqrt{4\pi\epsilon_{0}\epsilon_{4}}} \left[\frac{G^{2}}{\alpha_{2}}, \alpha_{2}^{2} + \frac{1}{\sqrt{4\pi\epsilon_{0}}\cdot\epsilon_{4}}, \frac{G^{2}\Omega_{2}^{2}}{\alpha_{2}}, \alpha_{2}^{2} \right] \right] + \frac{1}{\sqrt{4\pi\epsilon_{0}}\cdot\epsilon_{4}} + \frac{G^{2}}{\alpha_{2}}, \alpha_{2}^{2} + \frac{1}{\sqrt{4\pi\epsilon_{0}}\cdot\epsilon_{4}}, \frac{G^{2}\Omega_{2}^{2}}{\alpha_{2}}, \alpha_{2}^{2} + \frac{1}{\sqrt{4\pi\epsilon_{0}}\cdot\epsilon_{4}}, \frac{G^{2}\Omega_{2}}{\alpha_{2}}, \alpha_{2}^{2} + \frac{1}{\sqrt{4\pi\epsilon_{0}}\cdot\epsilon_{4}}, \frac{G^{2}\Omega_{2}}{\alpha_{2}}, \alpha_{2}^{2} + \frac{1}{\sqrt{4\pi\epsilon_{0}}\cdot\epsilon_{4}}, \alpha_{4}^{2} + \frac{G}{\alpha_{5}}, (-\alpha_{2}^{2}\alpha_{4}^{2} + \sqrt{3}_{2}^{2}\alpha_{4}^{2}) \right]$$

$$F_{A} = \frac{1}{2n\xi_{B}\xi_{J}} \left(\frac{G}{\alpha L} \left(\frac{V_{2}\alpha \chi^{2} + J_{3}\chi_{2}\alpha \chi^{3} - \alpha_{\chi}\alpha \chi + J_{3}\chi_{2}\alpha \chi^{3} \right) \right)$$

$$= \frac{1}{4n\xi_{0}\xi_{J}(\chi)} \left(\frac{G}{\alpha L} \chi J_{3}\alpha \chi^{3} \right)$$

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$$= \frac{1}{4n\xi_{0}\xi_{J}} \left(\frac{G}{\alpha L} \chi J_{3}\alpha \chi^{3} \right)$$

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$$= \frac{1}{4n\xi_{0}} \left(\frac{G}{\alpha L}$$

Stokes theorom Cip - normal cent verb $curl A = \nabla X A = \lim_{s \to 0} \frac{\phi_L A.dL}{A.s}$ 15 - Cirea board by curve Stokes theorem states that $\int_{L} A dl = \int_{S} \nabla x A ds$ considera cell ASK length KK $\oint A.dl = \underset{K}{\neq} \oint_{4K} A.dl$ $= \underset{K}{\neq} \oint \underset{LK}{Adl} AS_{K}$ $\int_{\Sigma} A dL = \underset{K \quad D_{SK} \rightarrow 0}{\leq} \int \frac{A dI}{\Delta_{SK}} \frac{\int_{SK} A dI}$ (1) If A= Scusp Ap + Sind ap 5 2

Ans

around the path shown in figure, confirm. Evaluate & A.dz this by stoke theorum. di= drap - 1 pdq . af + dz. az alob Spsind de + Spcosp. de + Spsind. de + Spcosp. de Bo

= 2((0530 - (0560) + (050)) + (050)

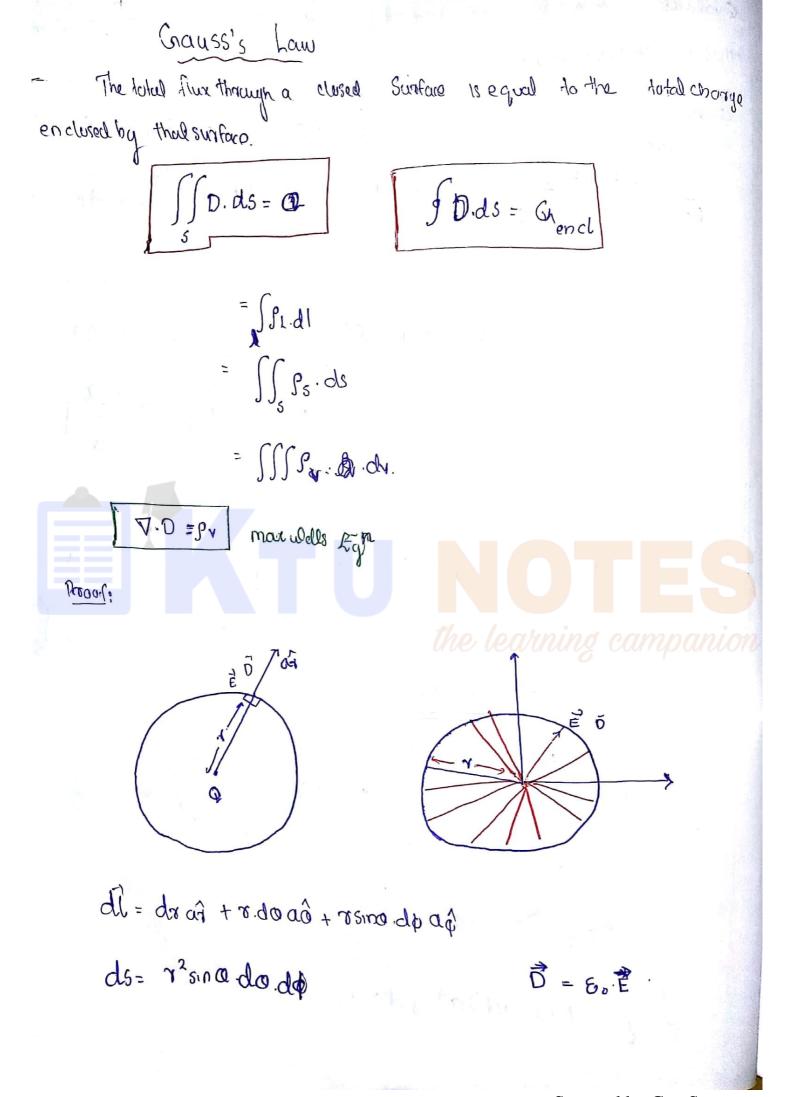
 $2 \times [\cos 60 - (\cos 30)] + (\cos 30) \times \frac{\beta^2}{2} \int_{2}^{5} + 2 \times [\cos 30 - 60]$ the let $\cos \cos x \left[\frac{g^2}{2} \right]_{=}^{2}$

 $\int_{30}^{60} \frac{5}{2} \int_{30}^{60} \frac{5}{2} a_p \int_{20}^{5} \frac{1}{2} a_q^2 a$

apt the sind.

pb ab a S (Sinp + Psinp) az . pdq ds

Ser Care I



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$$I_{el} D = \mathcal{E}_{0} \cdot \vec{\mathcal{E}}$$

$$\vec{\mathcal{E}} = \frac{1}{4\pi \mathcal{E}_{0}} \cdot \frac{\sigma}{q_{2}} \alpha_{1}^{2}$$

$$\vec{D} = -\frac{1}{4\pi} \cdot \frac{G}{q_{2}} \alpha_{1}^{2}$$

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$$\vec{O} \rightarrow 0 \pm 0.7$$

$$\vec{O} \rightarrow 0 \pm$$

$$F = \frac{1}{4\pi\epsilon_{0}} \cdot \frac{\alpha}{\pi^{2}} \cdot \alpha_{1}^{4}$$

$$D = \frac{1}{6\sigma} \cdot \frac{\alpha}{\pi^{2}}$$
Fads about a conductod

(17 E= 0, voside the conductod

(2) Thereforenage vesides on
the surface of the expected

(3) E' is perpendicular to the conductod on the Surface. ESS

(3) E' is perpendicular to the conductod on the Surface. ESS

Flectrostatic potential

It is the work dae in moving a test thange from one point to another

in a region of electric field.

 $W_{a \rightarrow b} = -\int_{a}^{b} F \cdot dt = -q \int_{a}^{b} E \cdot dt$

 $\frac{1}{q} = \int_{a}^{b} F \cdot dt = -q \int_{a}^{b} E \cdot dt$

 $\mathcal{L}^{(n)}$ $\mathcal{M}^{(n)}$

Polential clue to a pand charage
with charago
=
$$\frac{F \cdot dt}{q}$$

= $\frac{F \cdot dt}{q}$
= $\frac{F \cdot dt}{dt} = dts \cdot dt + a sino dt q \cdot q$
= $\frac{F \cdot dt}{q}$
= $-\int_{0}^{B} \frac{1}{2t} \cdot \frac{q}{q} \cdot dt$
= $-\int_{0}^{B} \frac{1}{2t} \cdot \frac{q}{q} \cdot dt$
= $-\int_{0}^{B} \frac{1}{q} \cdot \frac{q}{q} \cdot dt$
= $-\int_{0}^{B} \frac{1}{q} \cdot \frac{q}{q} \cdot dt$
= $\frac{Q}{4\pi E_0} \int_{0}^{R_0} \frac{1}{q^2} \cdot dt$
= $\frac{Q}{4\pi E_0} \int_{0}^{R_0} \frac{1}{R_0} - \frac{1}{R_0}$

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$$\begin{bmatrix}
V_{H0} = \frac{Q}{4R_{c_0}} \begin{bmatrix} \frac{1}{T_{B}} - \frac{1}{T_{A}} \end{bmatrix}$$
ebsalule poiendal
$$V_{\theta} = -\Phi \cdot \int_{\alpha}^{\theta} \frac{d}{4R_{c_0}} \times \frac{d}{T_{2}}$$

$$= -\int_{\alpha}^{\theta} \frac{d}{4R_{c_0}} \cdot \frac{1}{T_{A}}$$

$$V_{\theta} = -\int_{\alpha}^{\theta} \frac{d}{T_{A}} \cdot \frac{d}{T_{A}}$$

$$Note:$$

$$V_{R} = -V_{\theta} - V_{A}$$
More:

Podenticl us path undependent, undependent outjon the standing end

endung point us positions.

Prothest Method:
$$V_{\theta} = -\int_{\alpha}^{T_{A}} \frac{d}{T_{A}}$$

$$\frac{d}{T_{A}} \cdot \frac{d}{T_{A}} \cdot \frac{d}{T_{A}} \cdot \frac{d}{T_{A}}$$

$$\frac{d}{T_{A}} \cdot \frac{d}{T_{A}} \cdot \frac{d}{T_{A}} \cdot \frac{d}{T_{A}}$$

Here also the path is independent.

$$V_{h} = \int_{1}^{T_{h}} (E_{T} \cdot \alpha_{1}^{4}) \cdot dx \cdot \alpha_{1}^{4}$$

$$= \int_{0}^{T_{h}} E_{T} \cdot \alpha_{1}^{4} = \int_{0}^{T_{h}} \frac{1}{4\pi E_{0}} \frac{\alpha}{\tau_{2}} \cdot dx$$

$$= \frac{\alpha}{4\pi E_{0}} \cdot \frac{1}{\tau_{h}}$$

$$T_{h} = \frac{1}{\pi E_{0}} \cdot \frac{$$

$$\begin{array}{c} \vdots \int Edt=0 \quad \text{this is called potential - conservative.} \\ \hline \\ \hline \\ Derivation to proove \qquad E = -\nabla V \\ \hline \\ tot \quad v = -\int e^{-dt} \\ \hline \\ tot \quad v = -\int e^{-dt} \\ \hline \\ tot \quad v = -\int e^{-dt} \\ \hline \\ tot \quad v = -E^{-dt} \\ \hline \\ tot$$

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$$\frac{\partial N}{\partial \chi} = -E_{X} \qquad \frac{\partial N}{\partial y} = E_{Y} \qquad \frac{\partial N}{\partial \chi} = E_{X}.$$

$$E = E_{X} C_{X} \chi^{2} + E_{Y} a_{Y}^{2} + E_{X} a_{X}^{2}$$
put obsolve in the equation in E

$$\frac{\partial}{\partial x} e^{-1} + \frac{\partial N}{\partial y} a_{Y}^{2} + \frac{\partial N}{\partial z} a_{X}^{2})$$

$$= \left[\frac{\partial}{\partial x} a_{X}^{2} + \frac{\partial N}{\partial y} a_{Y}^{2} + \frac{\partial N}{\partial z} a_{X}^{2}\right]$$

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$$= \left[\frac{\partial}{\partial x} a_{X}^{2} + \frac{\partial N}{\partial y} a_{X}^{2} + \frac{\partial N}{\partial z} a_{X}^{2}\right]$$

$$= \left[\frac{\partial}{\partial x} a_{X}^{2} + \frac{\partial N}{\partial y} a_{X}^{2} + \frac{\partial N}{\partial z} a_{X}^{2}\right]$$

$$= \left[\frac{\partial}{\partial x} a_{X}^{2} + \frac{\partial N}{\partial y} a_{X}^{2} + \frac{\partial N}{\partial z} a_{X}^{2}\right]$$

$$= \left[\frac{\partial}{\partial x} a_{X}^{2} + \frac{\partial}{\partial y} a_{X}^{2} + \frac{\partial}{\partial y} a_{X}^{2}\right]$$

$$= \left[\frac{\partial}{\partial x} a_{X}^{2} + \frac{\partial}{\partial y} a_{X}^{2} + \frac{\partial}{\partial y} a_{X}^{2} + \frac{\partial}{\partial y} a_{X}^{2}\right]$$

$$= \left[\frac{\partial}{\partial x} a_{X}^{2} + \frac{\partial}{\partial y} a_{X}^{2} + \frac{\partial}{\partial y} a_{X}^{2} + \frac{\partial}{\partial y} a_{X}^{2}\right]$$

$$= \left[\frac{\partial}{\partial x} a_{X}^{2} + \frac{\partial}{\partial y} a_{X}^{2} + \frac{\partial}{\partial y} a_{X}^{2}\right]$$

$$= \left[\frac{\partial}{\partial x} a_{X}^{2} + \frac{\partial}{\partial y} a_{X}^{2} + \frac{\partial}{\partial y} a_{X}^{2}\right]$$

$$= \left[\frac{\partial}{\partial x} a_{X}^{2} + \frac{\partial}{\partial y} a_{X}^{2} + \frac{\partial}{\partial y} a_{X}^{2}\right]$$

$$= \left[\frac{\partial}{\partial x} a_{X}^{2} + \frac{\partial}{\partial y} a_{X}^{2}$$

z)

ndz)

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(*) Converticat D =
$$fz \cos^2 \varphi a \hat{z} \cdot C/m^2$$
, calculate the change claring
(1, $\overline{p}_{A_1}, \overline{z}$) and the lotal change enclosed by the cylinder
readins $1m$ with $-2 \le x \le 2m$
($\frac{\partial z}{\partial x} \operatorname{cl} \frac{\partial}{\partial y} + \frac{\partial}{\partial z} \operatorname{cl} \frac{\partial}{\partial x}$, $fz \cos^2 \varphi \cdot a \hat{z}$
($\frac{\partial z}{\partial x} \operatorname{cl} \frac{\partial}{\partial y} + \frac{\partial}{\partial z} \operatorname{cl} \frac{\partial}{\partial x}$, $fz \cos^2 \varphi \cdot a \hat{z}$
($\frac{\partial z}{\partial x} - \frac{\partial}{\partial y} + \frac{\partial}{\partial z} \operatorname{cl} \frac{\partial}{\partial x} + \frac{\partial}{\partial x} \operatorname{cl} \frac{\partial}{\partial x} + \frac{\partial}{\partial z} \operatorname{cl} \frac{\partial}{\partial x} + \frac{\partial}{\partial z} \operatorname{cl} \frac{\partial}{\partial x} + \frac{\partial}{\partial z} \operatorname{cl} \frac{\partial}{\partial x} + \frac{\partial}{\partial x} \operatorname{cl} \frac{\partial}{\partial x} \operatorname{cl} \frac{\partial}{\partial x} + \frac{\partial}{\partial x} \operatorname{cl} \frac{\partial}{\partial$

١

$$\int_{0}^{1} \left[\int_{2}^{2} (f^{2} \cos^{2} \phi) \cdot dx \right] \cdot d\phi \right] \cdot dx$$

$$= \int_{0}^{1} \int_{1}^{1} (f^{2} \cos^{2} \phi) \cdot dx] \cdot d\phi = \frac{1}{2}$$

$$= \int_{0}^{1} \int_{1}^{1} (f^{2} \cos^{2} \phi) \cdot dx] \cdot d\phi = \frac{1}{2}$$

$$\int_{-2}^{1} \int_{0}^{1} \frac{4\beta^{2}}{2} (\frac{1+\cos 2\phi}{2}) \cdot d\phi = \frac{1}{2}$$

$$= 4\beta^{2} \cdot \sqrt{2} \int_{1}^{1} \frac{4\beta^{2}}{2} \cdot d\beta = \frac{1}{4} \int_{1}^{1} \frac{4\beta^{2}}{2} \cdot d\beta$$

$$= 4\beta^{2} \cdot \sqrt{2} \int_{0}^{1} \frac{4\beta^{2}}{2} \cdot d\beta = \frac{1}{2} \int_{1}^{1} \int_{0}^{1} \frac{4\beta^{2}}{3} \frac{\beta^{2}}{3} = \frac{1}{2} \int_{1}^{1} \int_{0}^{1} \frac{4\beta^{2}}{3} \int_{0}^{1} \frac{\beta^{2}}{3} = \frac{1}{2} \int_{1}^{1} \int_{0}^{1} \frac{\beta^{2}}{3} \int_{0}^$$

(ii) calculate the workdone in moving a tom 10.11% charge from point A(1,30°, 120°) to be (4,90°,60°)

$$V_{AB} = \frac{W_{AB}}{G_{1}}$$

$$W_{AB} = G_{1}(V_{B}B)$$

$$= G_{1}(V_{B}-V_{A})$$

$$V_{B} = \frac{10}{42} \times \sin 90 \times (05(60))$$

$$= -2.5$$

$$V_{A} = 10 \times \sin 30 \quad (05(120))$$

$$= -2.5$$

$$W_{AB} = G_{1}(V_{B}-V_{A})$$

$$= \frac{10}{42} \times \sin 30 \quad (05(120))$$

$$= -2.5$$

$$W_{AB} = G_{1}(V_{B}-V_{A})$$

$$= \frac{34}{4} \times 10 = 28.125 \text{ M} \text{ Joule}$$

A charge dubbutes with spherical symmetry has density - $Sv = \begin{cases} for \\ R \end{cases}$, $0 \leq 7 \leq R$, find $i = 1 \\ R \end{bmatrix}$, $detomne \in evory$ $r = \begin{cases} r \\ 0 \end{cases}$, r > R

where.

$$S_{v} = \begin{cases} \frac{f_{o}r}{R} & 0 \leq r \leq R \\ 0 & r > R \end{cases}$$

case-I	(
OSISR	T T T
Chaussels Call	
$\iint_{S} D.ds = G_{A} = \iiint_{S} S_{V}.dV$	
$\iint_{S} D.ds = \iint_{S} D.ds = D \iint_{S} ds$	
$=$ $D4\pi r^2$	
- ake RHS SS Por. dv	15
$= \frac{f_0 r}{R} \int \int \int dv = \frac{f_0 r}{R} \times \frac{4}{3} \pi r$	
$= \frac{\int_{O} \sigma h_{Q}}{R} \times \frac{1}{3} \Lambda \eta^{3}$	rning campanion

$$D_{1} \overline{R}^{9^{2}} = \frac{g_{0} r}{R} \frac{4}{3} \overline{R}^{3}$$

$$D = \frac{g_{0} r^{2}}{3R}$$

$$D = \varepsilon_0 \cdot E$$

$$E = \frac{p_0 \tau^2}{\varepsilon_0} = \frac{\frac{p_0 \tau^2}{3R\varepsilon_0}}{\frac{3R\varepsilon_0}{3R\varepsilon_0}}$$

Case-(2) point on the spherical symmetry

$$\int_{s} D ds = G = \iiint S_{v} dv$$

$$\int_{s} D ds = \iint D ds = D \iint ds$$

$$\Rightarrow D 4 k^{2}$$

$$\iiint \int_{v} \int_{0}^{0} \frac{\sigma}{R} dv \qquad T = R$$

$$\iint \int_{v} T \sigma R \quad \text{then on the surface } T = R.$$

$$D = \int_{0}^{0} R^{2}$$

$$E = \frac{f_{0}R}{3E_{0}}$$

$$D = \int_{0}^{0} R^{2}$$

$$E = \frac{f_{0}R}{3E_{0}}$$

$$\int_{0}^{0} D ds = G = \iint \int_{0}^{0} f_{v} dv$$

$$\iint \int_{0}^{0} D ds = G$$

$$D \int_{0}^{1} ds = G$$

$$\begin{aligned}
D &= \frac{1}{4\kappa + 12} \int_{0}^{1} \frac{4}{3} \pi R^{3} \\
&= \frac{\beta_{0}}{3\kappa^{2}} \frac{R^{3}}{1 + \ln n} \quad D = \xi_{0} \cdot E \\
E &= \frac{\beta_{0}}{3\kappa^{2}} \frac{R^{3}}{2\epsilon_{0}\tau^{2}} \quad \text{cutside. the sphere} \\
&= \frac{\beta_{0}}{3\epsilon_{0}\tau^{2}} \quad \text{cutside. the sphere} \\
&= \frac{\beta_{0}}{3\epsilon_{0}\tau^{2}} \frac{R^{3}}{2\epsilon_{0}\tau^{2}} \\
\hline
Polendial \quad due ls \quad a \quad Cledenic \quad Dipple \\
&= \frac{1}{3\epsilon_{0}\tau^{2}} \quad \text{NOTES} \\
&= \frac{1}{4\kappa} \int_{0}^{1} \frac{4}{\tau^{2}} \int_{0}^{1} \frac{R^{3}}{\tau^{2}} \frac{R^{3}}{\tau^{2}} \\
\hline
Polendial \quad due ls \quad a \quad Cledenic \quad Dipple \\
&= \frac{1}{4\kappa} \int_{0}^{1} \frac{1}{\tau^{2}} \int_{0}^{1} \frac{R^{3}}{\tau^{2}} \frac{R^{3}}{\tau^{2}} \\
\hline
Polendial \quad due ls \quad a \quad Cledenic \quad Dipple \\
&= \frac{1}{4\kappa} \int_{0}^{1} \frac{1}{\tau^{2}} \int_{0}^{1} \frac{R^{3}}{\tau^{2}} \frac{R^{3}}{\tau^{2}} \\
\hline
Polendial \quad due ls \quad a \quad Cledenic \quad Dipple \\
&= \frac{1}{4\kappa} \int_{0}^{1} \frac{1}{\tau^{2}} \int_{0}^{1} \frac{R^{3}}{\tau^{2}} \frac{R^{3}}{\tau^{2}} \\
&= \frac{1}{4\kappa} \int_{0}^{1} \frac{1}{\tau^{2}} \int_{0}^{1} \frac{R^{3}}{\tau^{2}} \int_{0}^{1} \frac{R^{3}}{\tau^{2}} \frac{R^{3}}{\tau^{2}} \\
&= \frac{1}{4\kappa} \int_{0}^{1} \frac{1}{\tau^{2}} \int_{0}^{1} \frac{R^{3}}{\tau^{2}} \int_{0}^{1} \frac{R^{3}}{\tau^{2}} \int_{0}^{1} \frac{R^{3}}{\tau^{2}} \frac{R^{3}}{\tau^{2}} \\
&= \frac{1}{4\kappa} \int_{0}^{1} \frac{1}{\tau^{2}} \int_{0}^{1} \frac{R^{3}}{\tau^{2}} \int_$$

$$\begin{aligned} \left[et \ \pi_{1} \text{ can be written } \alpha \right] \\ \tau_{1} = \pi - AB \\ = \pi - L\cos \theta \\ \tau_{2} = \pi + Le\cos \theta \\ \tau_{1} = \pi + Le\cos \theta \\ \tau_{2} = \pi + Le\cos \theta \\ \tau_{1} = \pi + Le\cos \theta \\ \tau_{2} = \pi + Le\cos \theta \\ \tau_{1} = \pi + Le\cos \theta \\ \tau_{2} = \pi + Le\cos \theta \\ \tau_{1} = \pi + Le\cos \theta \\ \tau_{2} = \pi + Le\cos \theta \\ \tau_{2} = \pi + Le\cos \theta \\ \tau_{1} = \pi + Le\cos \theta \\ \tau_{2} = \pi + Le\cos \theta \\ \tau_{1} = \pi + Le\cos \theta \\ \tau_{2} = \pi + Le\cos \theta \\ \tau_{1} = \pi + Le\cos \theta \\ \tau_{2} = \pi + Le\cos \theta \\ \tau_{2} = \pi + Le\cos \theta \\ \tau_{2} = \pi + Le\cos \theta \\ \tau_{1} = \pi + Le\cos \theta \\ \tau_{2} = \pi +$$

$$= \frac{\partial V}{\partial \tau} cv_{1}^{2} + \frac{1}{\tau} \frac{\partial V}{\partial 0} cv_{0}^{2} + \frac{1}{\tau} cv_{0}^{2} cv_{1}^{2} + \frac{1}{\tau} \frac{\partial V}{\partial 0} cv_{1}^{2} + \frac{1}{\tau} cv_{0}^{2} cv_{0}^{2} +$$

1

$$= \frac{P(050)}{4\pi\epsilon_{0}} \frac{2}{24} \left(\frac{1}{7^{2}}\right) + \frac{P}{4\pi\epsilon_{0}7^{3}} \frac{2}{200} \cos 0 + \frac{Pc050}{734\pi\epsilon_{0}500}$$

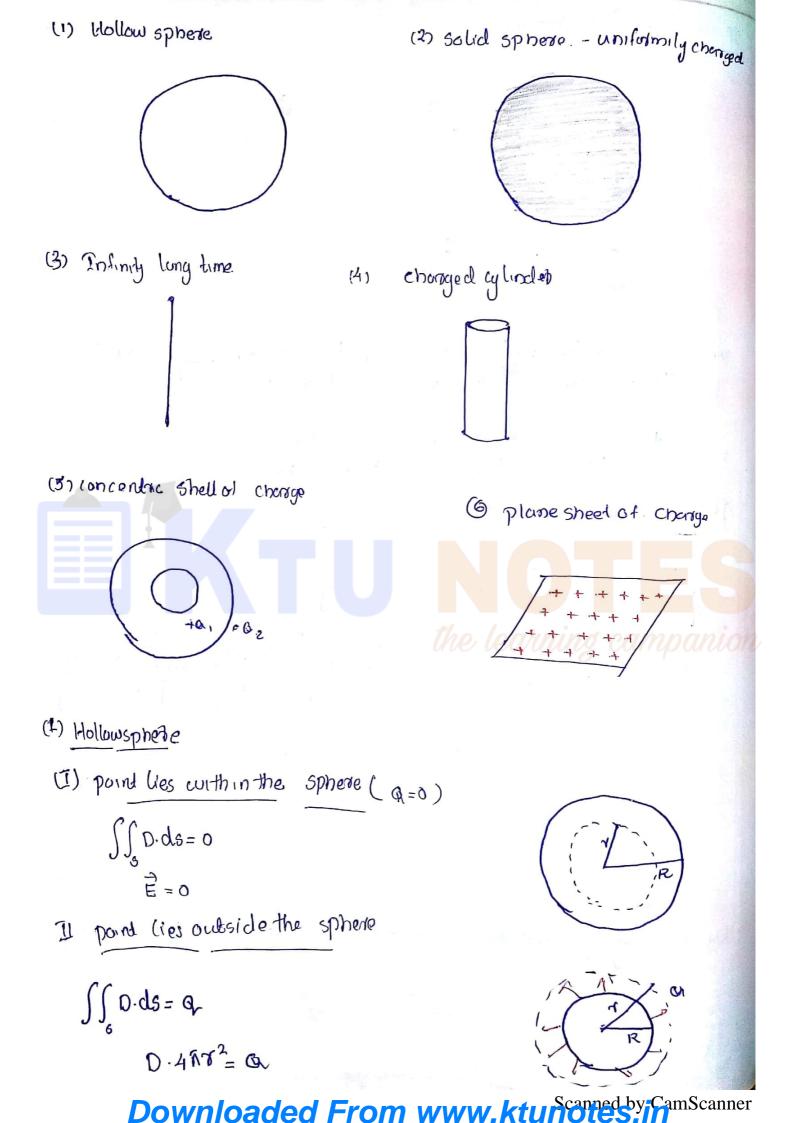
$$= \frac{Pc050}{4\pi\epsilon_{0}} = \frac{-220}{4\pi\epsilon_{0}} \left[(050 - \frac{2}{73}) \cos^{1} + \frac{1}{7} \times \frac{1}{7^{2}} - \sin 0 \cos^{1} + \frac{1}{7} \times \frac{1}{7^{2}} - \sin 0 \cos^{1} + \frac{1}{7} + \frac{1}{7} \times \frac{1}{7^{2}} - \sin 0 \cos^{1} + \frac{1}{7^{3}} \sin^{1} + \frac{1}{7} \times \frac{1}{7^{2}} + \frac{1}{7} \times \frac{1}{7} \frac{1}{7} \times \frac{1}{7} \times \frac{1}{7} + \frac{1}{7} \times \frac{1}{7} \times \frac{1}{7} \times \frac{1}{7} + \frac{1}{7} \times \frac{1}{$$

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Equipolential Surface
Equipolential Surface
Equipolential Surface
0 work done to b move change to Equipolential Surface become
zero (G.XV ng : w), Vng=0, then G=0
0 Two equipolential Surface bevet intersed each other
0 E is allows portroal to the surface.
Electro Static potential energy
1 dt v =
$$\frac{1}{4}$$
 $\frac{G_1}{R_2}$ $\frac{G_1}{R_2}$ G_2 G_3
Then workdone w = V.Q_2
= $\frac{1}{4nE_0} \cdot \frac{G_1 \cdot G_2}{R_{12}}$ $\frac{G_1}{R_{12}}$ $\frac{G_2}{R_{12}}$ $\frac{G_3}{R_{23}}$

11 we have hous charages

$$M = \frac{1}{4\pi\epsilon_{0}} \cdot \frac{G_{10}}{R_{11}} + \frac{1}{4\pi\epsilon_{0}} \cdot \frac{G_{2}}{G_{2}} + \frac{1}{4\pi\epsilon_{0}} \cdot \frac{G_{3}}{G_{3}} + \frac{1}{4\pi\epsilon_{0}} \cdot \frac{G_{10}}{G_{10}} + \frac{1}{4\pi\epsilon_{0}} \cdot \frac{G_{10}}{R_{10}} + \frac{1}{4\pi\epsilon_{0}} \cdot \frac{G_{2}}{G_{2}} + \frac{1}{4\pi\epsilon_{0}} \cdot \frac{G_{3}}{G_{3}} + \frac{1}{4\pi\epsilon_{0}} \cdot \frac{G_{3}}{G_{3}} + \frac{1}{4\pi\epsilon_{0}} \cdot \frac{G_{10}}{R_{10}} + \frac{1}{4\pi\epsilon$$



$$D = \frac{d}{4\pi\sigma^{2}}$$

$$E = \frac{d}{4\pi\varepsilon_{0}} \frac{d}{\tau^{2}} \alpha^{2}$$

$$\frac{d}{dt} = \frac{d}{t} \frac{d}{\tau^{2}} \alpha^{2}$$

$$\frac{d}{dt} = \frac{d}{\tau^{2}} \alpha^{2}$$

$$\frac{d}{dt} = \frac{d}{t} \frac{d}{\tau^{2}} \alpha^{2}$$

$$\frac{d}{dt} = \frac{d}{t} \frac{d}{\tau^{2}} \alpha^{2}$$

$$\frac{d}{t} \frac{d}{t} \frac{d}$$

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$$\int_{3}^{7} D ds = \Theta_{en}$$

$$D 4 \Lambda n^{2} = \frac{Q_{1} r^{3}}{R^{3}}$$

$$D = \frac{Q_{1}}{4\pi} \frac{r}{R^{3}}$$

$$E = \frac{Q_{1}}{4\pi\epsilon_{0}} \frac{r}{R^{3}}$$

$$(i) \text{ on the Surface}$$

$$r = R$$

$$E = \frac{1}{4\pi\epsilon_{0}} \frac{Q}{R^{2}}$$

$$(ii) \text{ point Lies out Side the sphere}$$

$$D \cdot 4Rr^{2} = Q$$

$$D = \frac{1}{4\pi\epsilon_{0}} \frac{QR}{r^{2}}$$

$$E = \frac{1}{4\pi\epsilon_{0}} \frac{QR}{r^{2}}$$

$$E = \frac{1}{4\pi\epsilon_{0}} \frac{QR}{r^{2}}$$

$$(5) \text{ concentric Shell of charge}$$

$$case (j) inside the shell$$

$$\iint_{S} D ds = 0$$

$$\vec{E} = 0$$

(Fi) Gi

$$\begin{aligned} \cos(2x) & \text{Between the Shell} \\ \iint_{S} 0.ds = Q_{1} \\ D \cdot 4\pi (Y_{2} - Y_{1})^{2} = G_{1} \\ D = \frac{Q_{1}}{4\pi (Y_{2} - Y_{1})^{2}} \\ \hline E = \frac{1}{4\pi \xi_{0}} \cdot \frac{Q_{1}}{4\pi (Y_{2} - Y_{1})^{2}} \\ \hline E = \frac{1}{4\pi \xi_{0}} \cdot \frac{Q_{1}}{4\pi (Y_{2} - Y_{1})^{2}} \\ \cos(2x) & \cos(2x) & \cos(2x) & \cos(2x) & \cos(2x) \\ (G_{2} + Q_{1}) & (G_{2} + Q_{1}) \\ D \cdot 2\pi (G_{2} + Q_{1}) & (G_{2} + Q_{1}) \\ D = \frac{(Q_{2} + Q_{1})}{4\pi (Y_{2} + Y_{1})^{2}} & (G_{2} + Q_{1}) \\ \hline E' = \frac{1}{4\pi \xi_{0}} \cdot \frac{(Q_{1} + Q_{2})}{(M_{2} + Y_{1})^{2}} & (G_{1} + Q_{2}) \\ \hline G_{1} & (G_{1} + Q_{2}) \\ \hline G_{2} & (G_{1} + Q_{2}) \\ \hline G_{2} & (G_{1} + Q_{2}) \\ \hline G_{2} & (G_{1} + Q_{2}) \\ \hline G_{1} & (G_{1} + Q_{2}) \\ \hline G_{2} & (G_{1}$$

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$$EP = \frac{Q}{2\pi \xi_{0}} \qquad E = \frac{Q}{2\pi \xi_{0}} \qquad \frac{1}{p_{0}}$$

$$E \quad \text{in linead change densit}$$

$$Q = g_{0} \times Q$$

$$D = \frac{f_{1}}{2\pi \xi_{0}} \times Q$$

$$P = \frac{f_{2}}{2\pi \xi_{0}}$$

$$E = \frac{f_{2}}{2\pi \xi_{0}}$$

$$E = \frac{f_{2}}{2\pi \xi_{0}}$$

$$E = \frac{f_{1}}{2\pi \xi_{0}}$$

$$C^{4} \text{ changed cylinder (chollow)}$$

$$(1) \text{ Roside the cylinder}$$

$$\int_{S} 0 \text{ cds} = 0$$

$$C^{4} \text{ changed cylinder}$$

$$\int_{S} 0 \text{ cds} = 0$$

$$C^{4} \text{ changed cylinder}$$

$$\int_{S} 0 \text{ cds} = 0$$

$$C^{4} \text{ changed cylinder}$$

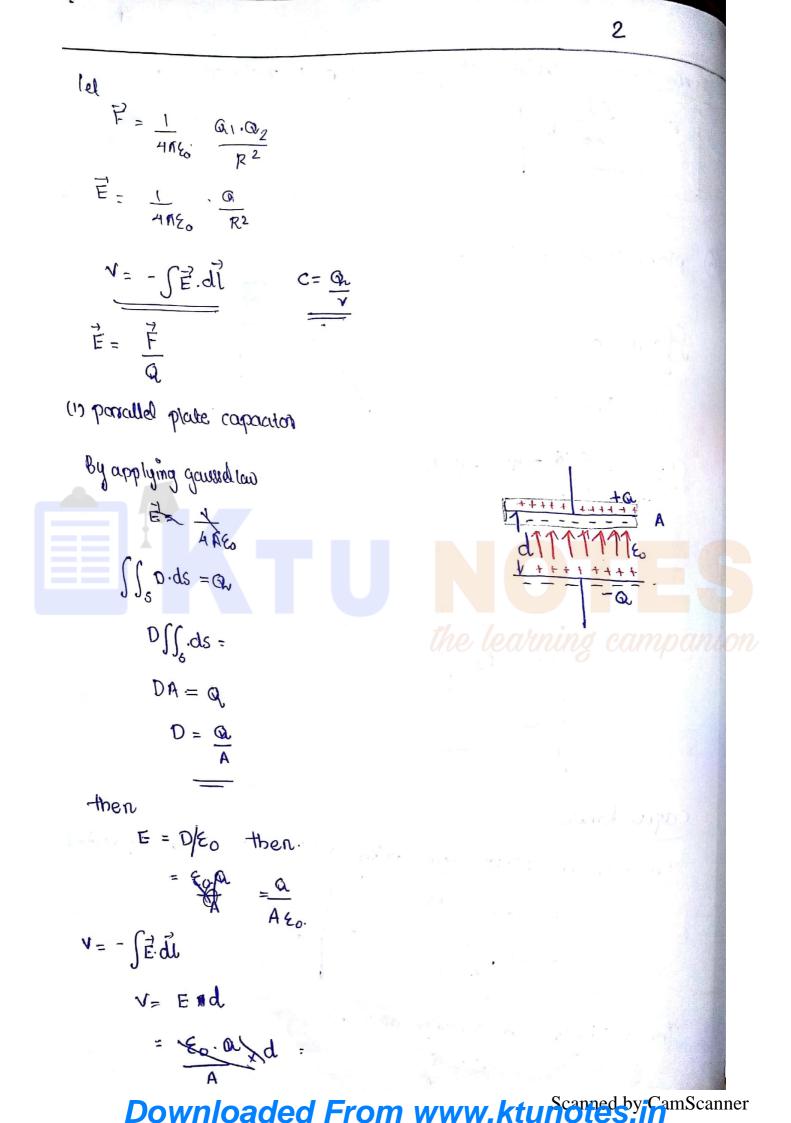
$$C^{4} \text{ changed cyli$$

Surface - on the serie of cylinds' take 'R' reclured cylinds

$$E = \frac{PR}{areo} R$$
(9) plane sheet of charge
$$\iint Dds = a = \frac{1}{16} \cdot ds$$

$$= \frac{1}{16} \cdot ds$$

$$\iint Dds = \frac{1}{16} \cdot \frac$$



$$F = \int dl \qquad C = \frac{Q}{V},$$

$$V = \mathcal{E}_{0} \cdot z \qquad = \frac{G}{Ed},$$

$$= \frac{G}{A_{E_{0}}}, zd$$

$$C = \frac{A \mathcal{E}_{0}}{A_{E_{0}}}, zd$$

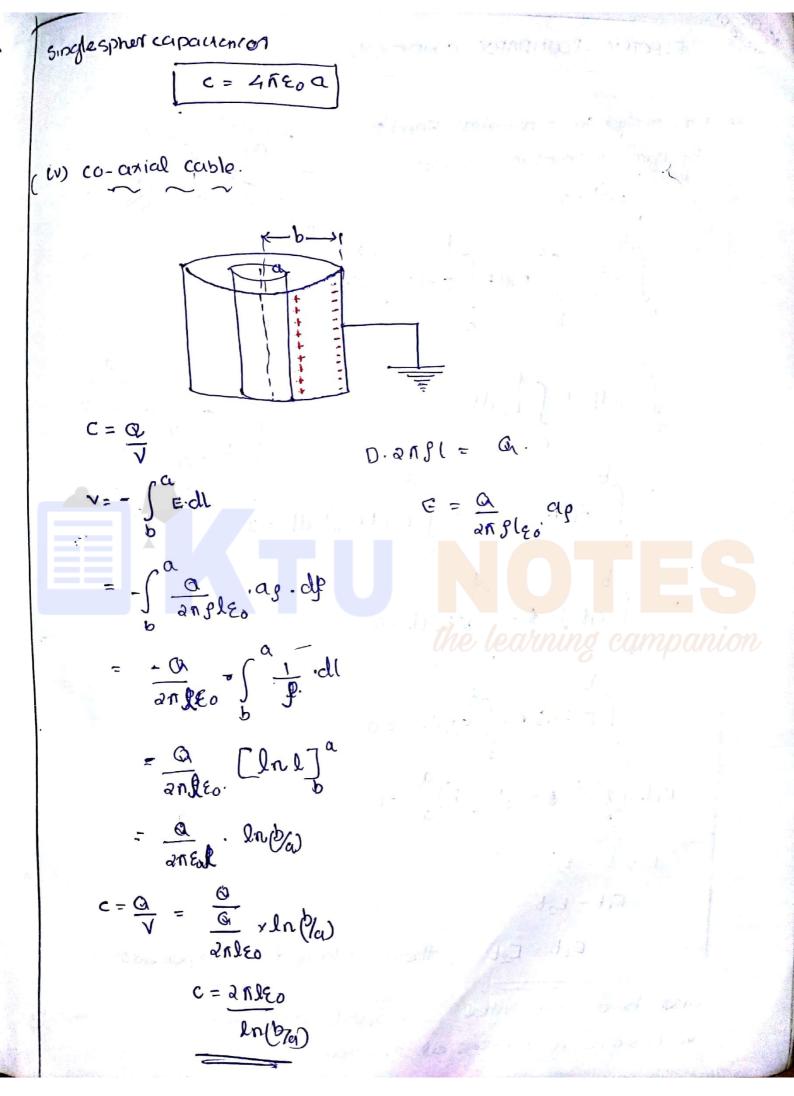
$$C = \frac{A \mathcal{E}_{0}}{d}, cr \qquad C = \frac{\mathcal{E}_{0} \cdot \mathcal{E}_{r} \cdot A}{d},$$

$$C = \frac{A}{d}, cr \qquad C = \frac{\mathcal{E}_{0} \cdot \mathcal{E}_{r} \cdot A}{d},$$

$$DA = Q,$$

$$D = \frac{Q}{A}, v = V, + V_{2} + V_{3} + V_{4}, v = E_{4}, v =$$

$$C = \frac{A}{\frac{1}{2}\left(1 + \frac{1}{2}\left(\frac{1}{2} + \frac{1}{2}\right)\left(\frac{1}{2} + \frac{1}{2}\right)\left(\frac{1}{2} + \frac{1}{2}\right)\left(\frac{1}{2} + \frac{1}{2}\right)}{\frac{1}{2}\left(1 + \frac{1}{2}\left(\frac{1}{2} + \frac{1}{2}\right)\left(\frac{1}{2} + \frac{1}{2}\right)\left(\frac{1}{2} + \frac{1}{2}\right)\left(\frac{1}{2} + \frac{1}{2}\right)}{\frac{1}{2}\left(1 + \frac{1}{2}\right)\left(\frac{1}{2} + \frac{1}{2}\right)\left(\frac{1}{2} + \frac{1}{2}\right)\left(\frac{1}{2} + \frac{1}{2}\right)}{\frac{1}{2}\left(1 + \frac{1}{2}\right)\left(\frac{1}{2} + \frac{1}{2}\right)\left(\frac{1}{2} + \frac{1}{2}\right)\left(\frac{1}{2} + \frac{1}{2}\right)\left(\frac{1}{2} + \frac{1}{2}\right)\right)}{\frac{1}{2}\left(1 + \frac{1}{2}\right)\left(1 + \frac{1}{2}\right)\left(\frac{1}{2} + \frac{$$



ELECTRIC BOUNDARY CONDITIONS

. Here analyse the parameters Eand D' meclum-2 El OI a h 3 h 20 By using conservative property \$Edl=0 madium (2;) $\int E dl + \int E dl + \int E dl + \int E dl = 0$ $= \int_{a}^{b} E_{1} d d + \int_{a}^{b} E_{2} d d$ E_{1} E_{1} E_{1} E_{1} E_{1} E_{1} = $\int (E_1 + E_1 n) \cdot d1 + \int (E_2 + E_2 n) \cdot d1 = 0$ $= \int_{E_1t}^{b} dt = \int_{E_2t}^{q} dt = 0$ $= \int_{E_1 \cdot t} dt \cdot \mathbf{0} - \int_{E_2 \cdot dt} dt = 0$ $E_{it} \left[l \right]_{a}^{b} = E_{2}t \left[l \right]_{c}^{d} = 0$ Eitl - Eill = 0 E1t- E2t =0 Eit = Ezt, these are tengential compenseds and here tangential componends of electroic field indensity. vectors are continues at the surface.

$$\begin{aligned} \iint Dds = q \quad gausses low \\ \iint D_{2}ds + \iint D_{1}ds = a \\ \iint (D_{2}ds + \iint (D_{1}ds = a) \\ f(D_{1}ds + \iint (D_{1}ds = a) \\ f(D_{2}t + D_{2}h) ds + \iint (D_{1}t + D_{1}h) ds = q \\ f(D_{2}t + D_{2}h) ds + \iint (D_{1}t + D_{1}h) ds = q \\ f(D_{2}s + D_{2}h) ds + \iint (D_{1}t + D_{1}h) ds = q \\ f(D_{2}s + D_{2}h) ds + \iint (D_{1}t + D_{1}h) ds = q \\ f(D_{2}s + D_{2}h) ds + \iint (D_{1}t + D_{1}h) ds = q \\ f(D_{2}s + D_{2}h) ds + \iint (D_{1}t + D_{1}h) ds = q \\ f(D_{2}s + D_{2}h) ds + \iint (D_{1}t + D_{1}h) ds = q \\ f(D_{2}s + D_{2}h) ds + \iint (D_{1}t + D_{1}h) ds = q \\ f(D_{2}s + D_{2}h) ds + \iint (D_{1}t + D_{1}h) ds = q \\ f(D_{2}s + D_{2}h) ds + \iint (D_{1}t + D_{1}h) ds = q \\ f(D_{2}s + D_{2}h) ds + \iint (D_{1}t + D_{1}h) ds = q \\ f(D_{2}s + D_{2}h) ds + \iint (D_{1}t + D_{1}h) ds = q \\ f(D_{2}s + D_{1}h) ds = f(D_{1}t + D_{1}h) ds = q \\ f(D_{2}s + D_{1}h) ds = f(D_{1}t + D_{1}h) ds = q \\ f(D_{2}h) ds = f(D_{1}h) ds = f(D_{1}h) ds = f(D_{1}h) ds \\ f(D_{1}h) ds = f(D_{1}h) ds = f(D_{1}h) ds \\ f(D_{1}h) ds = f(D_{1}h) ds = f(D_{1}h) ds \\ f(D_{1}h) ds = f(D_{1}h) ds = f(D_{1}h) ds \\ f(D_{1}h) ds = f(D_{1}h) ds = f(D_{1}h) ds \\ f($$

$$\begin{aligned} \mathcal{E}_{1} \mathcal{E}_{1} \cos \varphi_{1} &= \mathcal{E}_{2} \mathcal{E}_{2} \cos \varphi_{2} \quad \overrightarrow{\varphi} \\ & \overrightarrow{\varphi}_{1} &= \frac{1}{\varepsilon_{1}} \cos \varphi_{1} \\ & \overrightarrow{\xi}_{1} &= \frac{1}{\varepsilon_{2}} \\ & \overrightarrow{\xi}_{1} &= \frac{1}{\varepsilon_{2}} \\ & \overrightarrow{\xi}_{2} \\ & \overrightarrow{\xi}_{1} &= \frac{\varepsilon_{1}}{\varepsilon_{2}} \\ & \overrightarrow{\xi}_{2} \\ & \overrightarrow{\xi}_{$$

There is no tangential components in the case of sthe medium. becomes conduction and Diblectric. That is one of the mediu is concluctor :. Eit=0

the learning campanion